# THE STEFAN TYPE PROBLEM OCCURRING IN THE INVESTIGATION <br> OF SALT DISSOLUTION AND TRANSPORT PROCESS IN SOIL * 

V. E. KLYKOV, V. L. KULAGIN and V. A. MOROZOV

The boundary value problem associated with a parabolic equation whose coefficients become discontinuous from some instant of time along a beforehand unknown sliding line is considered. Such problem defines, for instance, the dissolution and removal of substances from the soil under hydraulic structure foundations, flushing of saliferous soils, etc.
A characteristic of the investigated processes is that they run in two stages. In the first, dissolution occurs throughout the filtration region, while the second is characterized by the emergence and increase with time of a zone of complete dissolution of the substance solid phase. Similar problems were considered earlier in /1-3/.

A numerical method using finite differences is proposed here. The existence and uniqueness of solutions of finite difference problems is proved, and an iteration process whose convergence is also proved is presented. Proof is also given of the convergence of solutions of finite difference problems to the solution of the input problem as pitch grid approaches zero, which confirms the existence of such solutions.

1. We pass to the formulation of the problem which for convenience we shall consider on the example of flushing saliferous soils. We examine a homogeneous layer of soil of depth $L$ containing noxious salts in solid and fluid states. Let us assume that the flushing water which may also contain salts permeates into the layer from its surface. The concentration of salts in the water is assumed to be $c_{*}>0$. 'rhe salt and filtration streams that take place under these conditions are one-dimensional and parallel to the $x$-axis with the soil surface taken as the reference plane. If at the initial instant of time the distribution of solid salts is such that their quantity increases with depth or remains constant, then, after some time from the commencement of flushing, a region of complete dissolution of salts is formed near the soil surface. That region is separated from the region containing solid phase salts by an a priori unknown shifting boundary $l(t)$, where $t$ is the time. The unknown concentrations of dissolved and solid salts are defined by functions $c(x, t)$ and $N(x, t)$, respectively. Functions $c(x, t), N(x, t)$, and $l(t)$ are determined in conformity with /3/ by the following equations:

$$
\begin{align*}
& m_{2} c_{t}=D c_{x x}-v(t) c_{x}-N_{t}  \tag{1.1}\\
& N_{t}:--\gamma\left(c^{*}-c\right) \\
& 0<x<L, \quad 0<t \leqslant t^{*} ; \quad l(t)<x<L, \quad t>t^{*} \\
& m_{1} c_{t}=D c_{x x^{*}}-v(t) c_{x} \\
& N(x, t) \equiv 0, \quad 0<x<l(t), t>t^{*} \\
& c(x, 0)=c^{*}, \quad N(x, 0)=N_{*}(x)>0 \\
& D c_{x}(0, t)=v(t)\left(c(0, t)-c_{*}\right), \quad c_{x}(L, t)=0, t>0 \\
& c(l(t)-0, t)=c(l(t)+0, t), \quad c_{x}(l(t)-0, t)=c_{x}(l(t)+0, t) \\
& N(l(t)+0, t) \cdots 0, t>t^{*}, t^{*}=\min \{t: N(0, t)-0\}
\end{align*}
$$

where $m_{1}$ and $m_{2}$ are coefficients of soil porosity, $D$ is the effective coefficient of diffusion, $v(l)$ is the filtration rate, $\gamma$ is the coefficient of the dissolution rate, $c^{*}$ is the saturation concentration, and $c_{*}$ is the concentration of salts in the water permeating the soil. The subscripts $x$ and $t$ at the unknown functions denote derivatives with respect to respective variables.

For problem (1.1) which defines the first stage of the process $0<t \leqslant t^{*}$ the following statement is valid /4,5/.

Lemma 1 , If the assumptions
$m_{2}>0, \quad D>0, \gamma>0, c^{*}-c_{*}>0 . \quad v^{*} \geqslant v(t) \geqslant v_{0}>0$
$v(t) \rightleftarrows C^{1}[0, T], \quad v^{\prime}(t) \geqslant 0, N_{*}(x) \rightleftharpoons C^{1}[0, L], \quad N_{*}^{\prime}(x) \geqslant a>0$
hold, then there exists a unique instant $i^{*}>0$ such that for $0<t \leqslant t^{*}$ a inique classical solution of problem (1.1) obtains, and the following estimates are valid:

$$
\begin{aligned}
& c_{*} \leqslant c(x, t)<c^{*} ; \quad 0 \leqslant c_{x}(x, t) \leqslant K_{0} ; \quad 0<a \leqslant N_{x}(x, t) \leqslant A \\
& \alpha_{0} \leqslant c_{t}(x, t) \leqslant 0
\end{aligned}
$$

where $A, K_{0}$, and $\alpha_{0}$ are constants dependent of the problem coefficients.
Below we examine only the second stage $\left(t>t^{*}\right)$, taking as the initial instant of time $t=t^{*}$ and functions $c_{0}(x)=c\left(x, t^{*}\right)$ and $N_{0}(x)=N\left(x, t^{*}\right)$ as the initial conditions. Note that the estimates of Lemma 1 are valid for these functions. We shall consider problem (1.1) on the above assumptions.

Definition. The set of three functions $c(x, t), N(x, t)$, and $l(t)$, such that $c(x, i)$ and $N(x, t)$ are continuous in $Q_{T}=[0, L] \times[0, T]$ satisfy the equations and the right-hand boundary condition in (1.1) in the classical sense, and the left-hand side one in the sense that $\lim _{x \rightarrow 0} D c_{x}(x, t)=v(t)\left(c(0, t)-c_{*}\right)$, will be called the solution of problem (1.1) for $t>t^{*}$. The condition of union of the derivative of $c_{x}$ on the curve $l(t)$ is satisfied in the sense that

$$
\lim _{\varepsilon \rightarrow 0}\left|c_{x}(l(t)-\varepsilon, t)-c_{x}(l(t)+\varepsilon, t)\right|=0
$$

Function $l(t) \in C[0, T]$ satisfies the equation $N(l(t), t)=0$.
2. To prove the existence of a solution of this problem we, first, pass to the finite difference problem, and shall prove the existence and uniqueness of its solution and, then, show that the sequence of finite difference problems converges to the solution of the input problem (1.1) as the gird pitch approaches zero.

Let us consider the sequence of grids

$$
w_{p}=\left\{x_{i}=i h_{l}, \quad t_{j}=\sum_{k=1}^{j} \tau_{k}, \quad i=0, \ldots, M, \quad j=1, \ldots, M\right\}
$$

where $\tau_{k}$ is selected so as to conform to the method of catching the shifting boundary at a node of the grid /6/. We select an implicit four point scheme and obtain the following finite difference equation:

$$
\begin{align*}
& m_{1}\left(c_{i}^{j}\right)_{t}=D\left(c_{i}^{j}\right)_{x x}-v^{j}\left(c_{i}^{j}\right)_{x}, \quad i=1, \ldots, j-1  \tag{2.1}\\
& m_{2}\left(c_{i}^{j}\right)_{t}=D\left(c_{i}^{j}\right)_{x x}-v^{j}\left(c_{i}^{j}\right)_{x}+\gamma\left(c^{*}-c_{i}^{j}\right), \quad i=j+1, \ldots, M-1 \\
& \left(N_{i}^{j}\right)_{t}=-\gamma\left(c^{*}-c_{i}^{j}\right)_{,} \quad i=j, \ldots, M \\
& D\left(c_{1}^{j}\right)_{x}=v^{j}\left(c_{0}^{j}-c_{*}\right)_{,} \quad\left(c_{M}^{j}\right)_{x}=0, \quad c_{i}^{j}=c_{0}\left(x_{i}\right), \quad i=0, \ldots, M \\
& \left(c_{i}^{j}\right)_{x}=\left(c_{j+1}^{j}\right)_{x}, \quad N_{j}^{j}=0, \quad j=1, \ldots, M \\
& \left(c_{i}^{j}\right)_{x}=\left(c_{i}^{j}-c_{i-1}^{j}\right) / h, \quad\left(c_{i}^{j}\right)_{x x}=\left(c_{i+1}^{j}-2 c_{i}^{j}+c_{i-1}^{j}\right) / h^{2}, \quad\left(c_{i}^{j}\right)_{t}=\left(c_{i}^{j}-c_{i}^{j-1}\right) / \tau_{j} \\
& \qquad \tau_{j}=N_{i}^{j-1} /\left(\gamma\left(c^{*}-c_{j}^{j}\right)\right), \quad j=1, \ldots, M \tag{2.2}
\end{align*}
$$

where the last equation was obtained from the equation $\left(N_{j}^{j}\right)_{l}=-\gamma\left(c^{*}-c_{j}^{j}\right)$ with allowance for condition $N_{i}{ }^{i}=0$.

For solving problem (2.1)-(2.2) we obtain a number of a prioriestimates.
Lemma 2. Let

$$
D>0, m_{1}>0, m_{2}>0, \gamma>0, c^{*}>c_{*}>0, v^{*} \geqslant v^{j} \geqslant v_{0}>0
$$

then the estimate

$$
c_{*} \leqslant c_{i}^{j} \leqslant c^{*}, \quad i=0, \ldots, M, j=1, \ldots, M
$$

is valid. The proof is based on the maximum principle $/ 7 /$.
Lemma 3, Let the conditions of Lemma 2 be satisfied and, furthermore

$$
\begin{aligned}
& v^{j} \geqslant v^{j-1}, \quad j=1, \ldots, M, . \quad \gamma>v^{*} K_{0} /\left(c^{*}-\dot{c_{M}}\right) \\
& K_{0}=\left(1+v^{*} h / D\right)^{M_{v^{*}} c^{*} / D}
\end{aligned}
$$

then the estimates

$$
\left(c_{i}^{3}\right)_{t} \leqslant 0,0 \leqslant\left(c_{i}^{j}\right)_{x} \leqslant K_{0}, i=0, \ldots, M, j=1, \ldots, M
$$

hola. We shall prove this by induction. From Lemma 1 we have $\left.0 \leqslant\left(c_{i}\right)_{x} \leqslant \kappa_{0}, \quad D\left(c_{i}\right)_{x x}-v^{\circ}\left(c_{i}\right)_{x}\right)_{i} \gamma\left(c^{*}-c_{i}{ }^{\circ}\right) \leqslant 0, \quad i=1, \ldots, M-1$
Let us prove that $\left(c_{i} \mathbf{1}\right) \leqslant 0$ by contradiction. Let

$$
\left.\max _{i=2, \ldots, M}\left(c_{i}^{1}\right)_{t}=\left\{c_{i_{0}}\right\}_{t}\right\rangle>0
$$

We shall consider the following cases:

1) $2 \leqslant i_{0} \leqslant M-1$ when we obtain the following contradictory inequality:

$$
\begin{aligned}
& \left.0 \times m_{t}\left(c_{i_{0}}{ }^{1}\right)_{1} \quad l\right)\left(c_{i}{ }^{1}\right)_{x x}-r^{1}\left(c_{i_{0}}{ }^{1}{ }_{x} \therefore \eta\left(c^{*}-c_{i_{0}}{ }^{1}\right) \leqslant D\left(c_{i_{0}}\right)_{x x}-v^{0}\left(c_{i_{v}}{ }^{2}\right)_{x}\right. \\
& \gamma\left(c^{*}-c_{i_{4}}\right)-i^{x}-c^{\infty} ;\left(r_{i_{i}}{ }^{0}\right)_{x}=0
\end{aligned}
$$

2) $i_{0}=1$, when from (2.1) we obtain

$$
\left.\left(c_{1}^{0}\right)_{x x}=-r_{1}\left(c_{1}^{1}\right)_{1}\right)_{x x} \geqslant 0
$$

On the other hand, the inductive assumption and the conditions of the lemma imply that

$$
D\left(c_{1}^{0}\right)_{x x} e^{0}\left(c_{1}^{0}\right)_{x}-Y\left(c^{*}-c_{1}^{o}\right) p^{*} K_{0}-Y\left(c^{*}-c_{X h}^{0}\right)<0
$$

which also yields a contradiction;
3) with $i_{0}=0$ and $i_{0}=M$, using the boundary conditions, we again obtain a contradiction. Hence $\left(c_{i}\right)_{l} \leqslant 0$.

Let us now assume that for $j=1, \ldots, n$ the unknown inequalities are satisfied, and prove their validity for $j=n+1$.

First we shall prove the inequality $\left(c_{i}{ }^{\prime \prime}\right)_{x} \geqslant 0$. by contradiction. We assume

$$
\min _{i=0, \ldots, M}\left(c_{i}^{n}\right)_{x}=\left(c_{i_{a}}{ }^{n}\right)_{x}<0
$$

Then, using the inductive assumption and Eqs. (2.1), we arrive at a contradiction for any $i_{0} \in[0: M]$, which means that $\left(c_{i}^{\prime \prime}\right)_{x} \geqslant 0$ for all $i=0, \ldots, M$.

To prove the inequality $\left(c_{i}\right)_{x} r K_{0}$ we use the left-hand boundary condition in (2.1) which yields

$$
\left(c_{1}^{n}\right)_{x} \leqslant v^{*}\left(c^{*}-c_{*}\right) / D
$$

Moreover, from the inductive assumption we have

$$
m_{2}\left(c_{i}^{n}\right)_{i}=D\left[\left(c_{i+1}^{n}\right)_{x}-\left(c_{i}^{n_{1}}\right)_{x}\right]-v^{n}\left(c_{i}^{\beta_{x}}\right)_{x}+\gamma\left(c^{*}-c_{i}^{n_{3}}\right) \leqslant 0
$$

from which directly follows that

$$
\left(c_{i}^{n}\right)_{x} \leqslant\left(1+v^{*} h / D\right)^{M_{i^{*}} c_{c}^{*} / D}
$$

Finally a proof similar to that of estimate $\left(c_{i}\right)_{k} \leqslant 0$ shows that $\left(c_{i}^{(n+1)}\right)_{t} \leqslant 0$.
Lemma 4, If the conditions of Lemma 3 are satisfied and $c_{1 i}{ }^{\text {ib }}$ and $c_{2 i}{ }^{n}$ are the respective solutions of problem (2.1) for $\tau_{n}=\tau_{1 n}$ and $\tau_{n}=\tau_{2_{n}}$, then when $\tau_{2_{n}}>\tau_{1 n}$, we have $c_{2 i}{ }^{n} \leqslant c_{1 i}{ }^{n_{n}}$, $i=0, \ldots, M$.

To prove this we examine the remainder $z_{i}{ }^{n}=c_{2 i}{ }^{n}-c_{1 i}{ }^{n}$.
Function $z_{i}{ }^{n}$ satisfies the following equations:

$$
\begin{aligned}
& m_{i}^{2} i_{i}^{n} / \tau_{1 n}+\left(c_{1 i}^{n}\right)_{i}\left(\tau_{1 n} / \tau_{2 n}-1\right)=D\left(c_{i}^{n}\right)_{x 3}-v_{2}^{n}\left(v_{i}^{n}\right)_{x}-\gamma_{i}^{z_{i}^{n}-\left(v_{2}^{n}-v_{1}^{n}\right)\left(c_{1 i}^{n}\right)_{x}} \\
& i=1, \ldots, n-1, \quad m_{i}=m_{i}, \quad \gamma_{i}=0 \\
& i=n+1, \ldots, M-1, \quad m_{i}=m_{2}, \quad \gamma_{i}=\gamma \\
& \left(\varepsilon_{n}^{n}\right)_{x x}=0, \quad D\left(v_{i}^{n}\right)_{x}=\sigma_{2}^{n} n_{-i}^{n},\left(v_{2}^{n}-v_{1}^{n}\right)\left(c_{10}^{n}-c_{*}\right), \quad\left(s_{M}^{n}\right)_{x}=0
\end{aligned}
$$

Using the indirect proof method and taking into account the estimates of Lemmas 2 and 3 , we find that $z_{i}{ }^{n} \leqslant 0, i=0, \ldots, M$, hence $c_{2 i}{ }^{n} \leqslant c_{i}{ }^{n}$.

Lemma 5, If the conditions of Lemma 3 are satisfied, then the estimates

$$
\begin{aligned}
& 0<H_{0} \leqslant \tau_{j} / i \because M^{*}, \quad j \ldots 1, \ldots, M ; 0<a \leqslant\left(N_{i}\right)_{n} \leqslant \\
& K_{2}, \quad i=0, \ldots, M \\
& N_{i}^{j+1} \geqslant a h>0
\end{aligned}
$$

where $I_{0}, I^{*}$, and $K z$ are constants independent of $\tau_{j}$ and $h$, are valid.
Indeed, from the equation $\left(N_{i}{ }^{3}\right)=-\gamma\left(c_{1}^{*}-c_{t}{ }^{5}\right)$ we have

$$
\begin{align*}
& v_{i}^{j}-N_{i}^{0}=-\sum_{k=1}^{j} \tau_{k} \eta\left(c^{*}-\varepsilon_{i}^{k}\right)  \tag{2,3}\\
& \left(N_{i}^{j}\right)_{x}=\left(N_{i}^{0}\right)_{x}-\sum_{k=1}^{j} \tau_{h} y\left(c_{i}^{k}\right)_{x}
\end{align*}
$$

Using Eq. (2 2) for $x_{j}$ we obtain

$$
\begin{equation*}
\frac{\boldsymbol{r}_{j}}{h}=\left[\left(N_{j}{ }^{j}\right)_{x}+\sum_{k=1}^{j-1} \tau_{k} \gamma\left(c_{j}^{k}\right)_{x}\right] /\left(\gamma\left(c^{*}-c_{j}^{j}\right)\right) \tag{2.4}
\end{equation*}
$$

from which immediately follows the lower bound $\tau_{j} / h \geqslant a / \rho_{0}^{*}$. To obtain the upper bound $\tau_{j} / h$ we derive the following inequality:

$$
\frac{\mathrm{r}_{j}}{h} \times\left(A+\gamma K_{0} \sum_{k=1}^{j-1} \tau_{k}\right) /\left(\gamma\left(c^{*}-c_{M}^{*}\right)\right)
$$

which we write in the form

$$
t_{j} \leqslant\left(1+h K_{0} /\left(e^{*}-c_{M}{ }^{*}\right)\right) t_{i-1}+h A /\left(\gamma\left(\varepsilon^{*}-c_{M}{ }^{0}\right)\right)
$$

Using this inequality we obtain the following estimates:

$$
t_{j} \leqslant\left(1+h K_{0} /\left(c^{*}-c_{M}{ }^{\circ}\right)\right)^{j-1} A / \gamma K_{0} \leqslant C_{1}
$$

The necessary estimate now follow directly from equalities (2.3) and (2.4).
Lemma 6. If the conditions of Lemma 3 are satisfied and $\left(v^{j}-v^{j-1}\right) / \tau_{j} \leqslant P$, then there exists such $K_{1}<0$ independent of $h$ and $\tau_{j}$ that

$$
\left(c_{i}^{j}\right)_{t} \geqslant K_{1}, \quad i=0, \ldots, M, \quad j=1, \ldots, M
$$

The proof is by induction. From Lemma 1 we have the estimate

$$
m_{2} \alpha_{0} \leqslant D\left(c_{i}^{0}\right)_{x x}-v^{\circ}\left(c_{i}^{0}\right)_{x} \mid \gamma\left(c^{*}-c_{i}^{0}\right), \quad a_{0}<0
$$

We shall prove that $\left(c_{i}\right)_{t} \geqslant \alpha_{1}$, where

$$
a_{1}<\min \left\{\left(m_{2} a_{0}-P K_{0} \tau_{1}\right) /\left(m_{2}+\gamma \tau_{1}\right), \quad-P\left(c^{*}-c_{*}\right) / \nu_{0}\right\}
$$

Let us assume the opposite:

$$
\min _{i=0, \ldots, M}\left(c_{i}^{1}\right)_{t}=\left(c_{i_{0}}\right)_{t}<\alpha_{1}
$$

and first consider the case of $\quad i_{0}=1$. We have $D\left(c_{1}\right)_{x x}=0$ and $D\left(c_{1}\right)_{x x}-\nu^{0}\left(c_{1}\right)_{x}+\gamma\left(c^{*}-c_{1}{ }^{\circ}\right) \geqslant m_{2} \alpha_{0}$. Hence

$$
\begin{align*}
& \tau_{1} D\left(-\left(c_{1}^{1}\right)_{t}\right)_{x x}-v^{\circ}\left(c_{1}^{\circ}\right)_{x}+\gamma\left(c^{*}-c_{1}^{\circ}\right) \geqslant m_{2} \alpha_{0}  \tag{2.5}\\
& \left(c_{1}^{1}\right)_{t}-\left(c_{0}^{1}\right)_{t} \geqslant h^{2}\left(m_{2} a_{0}-\gamma c^{*}\right) /\left(D \tau_{1}\right)
\end{align*}
$$

On the other hand, from the boundary conditions in (2.1) we have

$$
\begin{equation*}
\left(c_{1}{ }^{1}\right)_{t}-\left(c_{1}\right)_{t}=\left[v^{1} \tau_{1}\left(c_{0}\right)_{t}+\left(v^{2}-v^{\circ}\right)\left(c_{0}{ }^{\circ}-c_{*}\right)\right] h /\left(D \tau_{1}\right) \tag{2.6}
\end{equation*}
$$

From (2.5) - (2.6) for a fairly small $h>0$ we obtain the inequality

$$
0 \leqslant\left(m_{2} \alpha_{0}-\gamma c^{*}\right)\left(h / \tau_{1}-v^{1 / l^{2}} / D \tau_{1}\right)+\left(c^{*}-c_{*}\right)\left(v^{1}-v^{\circ}\right) / \tau_{1}+v^{1} \alpha_{1} \leqslant
$$

$$
P\left(c^{*}-c_{*}\right)+v^{\circ} a_{1}
$$

However by virtue of the selection $\alpha_{1} P\left(c^{*}-c_{*}\right)+v^{\circ} \alpha_{1}<0$, i.e. the obtained inequality is constradictory. The case of $i_{0} \neq 1$ also results in a contradiction. Hence $\left(c_{i}\right)_{t} \geqslant \alpha_{1}$.

Let us now assume that for all $k=1, \ldots, n-1$ the inequality $\left(c_{i}{ }^{k}\right)_{t} \geqslant \alpha_{k}$ is satisfied and show that the $\left(c_{i}{ }^{n}\right)_{t} \geqslant \alpha_{n}$, where $a_{n}<0$ is chosen from the condition

$$
\begin{aligned}
& \alpha_{n}<\min \left\{\frac{m_{2} \alpha_{n-1}-P K_{0} \tau_{n}}{m_{2}+\gamma \tau_{n}},-\frac{v^{*} K_{0}}{m_{1}},-\frac{2\left(2 \gamma^{*}+v^{*} K_{0}\right)}{m_{1}-m_{2}}, \alpha_{n}^{*}+\right. \\
& \left.\quad \frac{m_{2} \alpha_{n-1}-\gamma c^{*}}{D \tau_{n}} h^{2}\right\} \\
& \alpha_{n}^{*}<\min \left\{\alpha_{n-1}-P K_{0} \tau_{n} / m_{1}, \quad-P\left(c^{*}-c_{*}\right) / v_{0}\right\}
\end{aligned}
$$

First we point out that $\left(c_{i}\right)_{t}$ cannot attain a local minimum smaller than $a_{n}{ }^{*}$ for $i=0, \ldots$, $n-2$. This is proved by contradiction with allowance for the boundary conditions in (2.1).

Let us now show that $\left(c_{i}{ }^{n}\right)_{t} \geqslant \alpha_{n}$ for all $i=0, \ldots, M$.
Let us assume that

$$
\min _{i=0, \ldots, M}\left(c_{i}{ }^{n}\right)_{t}=\left(c_{i_{0}}{ }^{n}\right)_{i}<\alpha_{n}
$$

Since $\quad \alpha_{n}<\alpha_{n}{ }^{*}$, this minimum cannot by virtue of the above remark be attained for $i_{0}-0$, $\ldots, n-2$. Let us consider the remaining cases:
a) $i_{0}=n-1$. We have $D\left(c_{n-1}^{n}\right)_{x x}=m_{1}\left(c_{n-1}^{n}\right)_{1}+v^{n}\left(c_{n-1}^{n}\right)_{x}$ and $D\left(c_{n-1}^{n-1}\right)_{x x}=0$. Then because of the selection of $\alpha_{n}<0$

$$
0 \leqslant \tau_{n} D\left(\left(c_{n-1}^{n-1}\right)_{t x x}=m_{1}\left(c_{n-1}^{n}\right)_{t}+v^{n}\left(c_{n-1}^{n}\right)_{x}<m_{1} a_{n}+v^{*} K_{0}<0\right.
$$

The obtained contradiction shows that this case is impossible.
b) $\quad i_{0}=n$. In this case $D\left(c_{n}^{n}\right)_{x x}=0$ and $D\left(c_{n 2}^{n-1}\right)_{x x}=m_{1}\left(c_{n}^{n-1}\right)_{t}+v^{n-1}\left(c_{n}^{n-1}\right)_{x}-\gamma\left(c^{*}-c_{n}^{n-1}\right)$ from which follows the inequality

$$
\begin{equation*}
0 \leqslant\left(c_{n-1}^{n}\right)_{1}-\left(c_{n}^{n}\right)_{1} \leqslant\left(-m_{2} \alpha_{n-1}+\gamma c^{*}\right) h^{2} /\left(D \tau_{n}\right) \tag{2.7}
\end{equation*}
$$

Let us prove that $\left(c_{n-1}^{n}\right)_{t} \leqslant\left(c_{n-2}^{n}\right)_{t}$ by assuming that $\left(c_{n-1}^{n}\right)_{t}>\left(c_{n-2}^{n}\right)_{i}$. Then from (2.7) we obtain

$$
\min _{i=0, \ldots, n-2}\left(c_{i}^{n}\right)_{t} \leqslant\left(c_{n-2}^{n}\right)_{t}<\left(c_{n-1}^{n}\right)_{t} \leqslant\left(c_{n}^{n}\right)_{t}+\left(-m_{2} \alpha_{n-1}-\gamma^{*}\right) h^{*} / D \tau_{n}<\alpha_{n}^{*}
$$

However, as previously shown, $\left(r_{i}{ }^{\prime \prime}\right) \ell$ cannot attain for $i=0, \ldots, n-2$ a minimum smaller than $\alpha_{n}{ }^{*}$. Hence the above assumption is false, and in fact $\left(r_{n-1}^{n}\right)_{l} \leqslant\left(c_{n-2}^{n}\right)_{t}$.

Then we have

$$
D\left(c_{n-1}^{n-1}\right)_{x x}=0, \quad D\left(c_{n-1}^{n}\right)_{x \cdot x}=m_{1}\left(c_{n-1}^{n}\right)_{l} ; v^{n}\left(e_{n-1}^{n}\right)_{x}
$$

By subtracting the first equality from the second we obtain

$$
\left[\left(c_{n}^{n}\right)_{t}-\left(r_{n-1}^{n}\right)_{t}\right] D \tau_{n} / h^{2}=\left[\left(r_{n-1}^{n}\right)_{t}-\left(r_{n-2}^{n}\right)_{t}\right] D \tau_{n} / L^{2} \cdot \mid-m_{1}\left(r_{n-1}^{n}\right)_{t}+v^{n}\left(c_{n-1}^{n}\right)_{x}
$$

from which with allowance for (2.7) and the inequality $\left(c_{n-1}^{n}\right)_{t} \leqslant\left(c_{n-2}^{n}\right)$ we obtain

$$
\begin{aligned}
& m: \alpha_{n}-\gamma_{1}^{*} \leqslant m_{2} \alpha_{n-1}-\gamma c^{*} \leqslant\left[\left(c_{n}{ }^{n}\right)_{i}-\left(c_{n-1}^{n}\right)_{l}\right] D \tau_{n} / h^{2} \leqslant m_{1} \alpha_{n}+\left(-m_{2} x_{n}+\right. \\
& \left.\because \cdots^{*}\right) m_{1} h^{2} /\left(D \tau_{n}\right)-v^{*} \kappa_{0}
\end{aligned}
$$

This inequality yields the following:

Taking into account the selection of $\alpha_{n}$ with a fairly small $h>0$ we obtain a contradictory inequality. Hence $\left(c_{i}{ }^{\prime \prime}\right), a_{n}, i=0, \ldots, M$, which shows the existence of constant $h_{1}, 0$ such that $\quad\left(c_{i}{ }^{n}\right)_{i} \geqslant K_{1}, i=0, \ldots, M, n=1, \ldots, M$.
3. Let us now investigate the problem of existence of solution of problem (2.1)-(2.2).

Theorem 1. If the condition of Lemma 3 is satisfied, the problem (2.1)-(2.2) has a unique solution.

Proof, Let us first assume that $\tau_{j}, j=1, \ldots, M$ are known. The solution of problem (2.1)- (2.2) can then be obtained by the method of run-through in explicit form /7/, and such solution is unique an continuously dependent on $\tau_{j}$. We shall now show that a $\tau_{j}$ that satisfies Eq. (2.2) exists. For this we examine function

$$
\Phi(\tau)=\tau-N_{j}^{j-1} /\left(\gamma\left(c^{*}-c_{j}^{j}\right)\right)
$$

By virtue of Lemma $5 \lim _{\tau \rightarrow 0} \Phi(\tau)<0$ as $\tau \rightarrow 0$, and for fairly large $\tau>0-\Phi(\tau)>0$. This with the continuity of function $\Phi(\tau)$ implies the existence of such $\tau{ }^{*}$ that

$$
\tau_{j}^{*}=N_{j}^{j-1} /\left(\gamma\left(c^{*}-\left(c_{j}^{j}\right)^{*}\right)\right)
$$

Let us prove the uniqueness of $\quad \tau^{*}, j=1, \ldots, M$. We set $j=1$ and assume the existence of the following two solutions of problem (2.1)-(2.2): $\tau_{1}{ }^{*}, c_{1 i}{ }^{1}, N_{1 i}{ }^{1}$ and $\tau_{1}{ }^{* *}, c_{2 i}{ }^{1}$, $N_{2 i}{ }^{1}$. For definites we set $\tau_{1}{ }^{*}<\tau_{1}{ }^{* *}$.

Then taking into account Lemma 4 we obtain

$$
\begin{gathered}
0<\tau_{1}^{*}-\tau_{1}^{* *}=N_{1}^{\circ} /\left(\gamma\left(c^{*}-c_{11}^{1}\right)\right)-N_{1}^{0} /\left(\gamma\left(c^{*}-c_{21}^{1}\right)\right)= \\
N_{1}^{0}\left(c_{21}^{1}-c_{11}^{1}\right) /\left(\gamma\left(c^{*}-c_{21}^{1}\right)\left(c^{*}-c_{11}^{1}\right)\right) \leqslant 0
\end{gathered}
$$

We have thus obtained a contradiction. Since the case of $\tau_{1}{ }^{*}>\tau_{1}{ }^{* *}$ also results in a contradiction, hence $\tau_{1}{ }^{*}=\tau_{1}^{* *}$. We similarly establish by induction that $\tau_{j}^{*}=\tau_{j}^{* *}, j=2$, .., $M$. The theorem is proved.

Let us consider the question of numerical solution of problem (2.1)-(2.2) in more detail.
Let us consider the following iteration process:

$$
\begin{aligned}
& m_{1}\left(c_{i n}^{(s)}\right)_{t}=D\left(c_{i n}^{(s)}\right)_{x x}-v^{n}\left(c_{i n}^{(s)}\right)_{x}, \quad i=1, \ldots, n-1 \\
& m_{2}\left(c_{i n}^{(s)}\right)_{t}=D\left(c_{i n}^{(s)}\right)_{x x}-v^{n}\left(c_{i n}^{(s)}\right)_{x}+\gamma\left(c^{*}-c_{i n}^{(s)}\right), \quad i=n+1, \ldots, M-1 \\
& D\left(c_{1 n}^{(s)}\right)_{x}=v^{n}\left(c_{0 n}^{(s)}-c_{*}\right), \quad\left(c_{M n}^{(s)}\right)_{x}=0, \quad\left(c_{n n}^{(\mathrm{s})}\right)_{x x}=0 \\
& \left(c_{i n}^{(\mathrm{s})}\right)_{t}=\left(c_{i n}^{(\mathrm{s})}-c_{i n-1}^{(\mathrm{s})}\right) / \tau_{n}^{(s)}, \quad\left(c_{i n}^{(s)}\right)_{x}=\left(c_{i n}^{(\mathrm{s})}-c_{i-1 n}^{(s)}\right) / h
\end{aligned}
$$

The recurrent approximation of $\tau_{n}^{(i+1)}$ is determined using formulas

$$
\begin{aligned}
& \tau_{n}^{(s+1)}=\left(a_{i+1}+b_{s+1}\right) / 2 \\
& A_{\mathrm{s}}=N_{n-1}^{n-1} /\left(\gamma\left(c^{*}-c_{n+1}^{(\cdot)}\right)\right)<\tau_{n}^{(\cdot)}, \quad a_{\mathrm{s}+1}-a_{\mathrm{s}}, \quad b_{\mathrm{s}+1}=\tau_{n}^{(s)} \\
& A_{\mathrm{s}} \geqslant \tau_{n}^{(-)}, \quad a_{s+1}=\tau_{n}^{(s)}, \quad b_{i+1}=b_{\mathrm{s}} \\
& \tau_{n}^{(0)}=N_{n}^{n-1} / \gamma c^{*}, \quad a_{1}=N_{n}^{n-1} / \gamma^{*}, \quad b_{1}=N_{n}^{n-1} / \gamma\left(c^{*}-c_{n n}^{(0)}\right)
\end{aligned}
$$

For a given $\tau_{n}{ }^{(s+1)}$ function $c_{i n}{ }^{(s+1)}$ is computed by the run-through method.
Theorem 2, If conditions of Lemma 3 are satisfied, the considered here process converges to the solution of problem (2.1)-(2.2).

Proof, The existence of solution $\tau_{n}, r_{i}{ }^{\prime \prime}, i=0, \ldots, M$ follows from Theorem 1 . Let us prove that $\tau_{n} \in\left[\tau_{n}{ }^{(s)}, A_{8}\right]$. For definiteness we assume that $\tau_{n} \leqslant \tau_{n}^{(\cdot)}$. We have

$$
A_{s}-\tau_{n}=N_{n}^{n-1} /\left(\gamma\left(c^{*}-c_{n n}^{(s)}\right)\right)-N_{n}^{n-1} /\left(\gamma\left(c^{*}-c_{n}^{n}\right)\right)
$$

Lemma 4 implies that $c_{m}{ }^{(\cdot)} \leqslant c_{n}{ }^{n}$, hence $A_{s}-\tau_{n} \leqslant 0$ or $A_{s} \leqslant \tau_{n}$. The case of $\tau_{n} \geqslant \tau_{n}{ }^{(\cdot)}$ is similarly considered. Thus, either $\tau_{n}^{(s)} \leqslant \tau_{n} \leqslant A_{g}$ or $A_{s} \leqslant \tau_{n} \leqslant \tau_{n}^{(-)}$. We shall now prove that for any $s \geqslant 1, \tau_{n} \in\left[a_{s}, b_{s}\right]$. Indeed, for $s=1$

$$
\tau_{n}^{(0)}=a_{1}=N_{n}^{n-1} / \gamma c^{*} \leqslant N_{n}^{n-1} /\left(\gamma\left(c^{*}-c_{n}{ }^{\eta}\right)\right)=\tau_{n}
$$

On the other hand, since $\tau_{n} \geqslant \tau_{n}{ }^{(0)}$ hence by virtue of Lemma 4

Thus $\tau_{n} \in\left[a_{1}, b_{1}\right]$.

$$
\tau_{n}-b_{\mathbf{1}}=\tau_{n}-\frac{N_{n}^{n-1}}{\gamma\left(c^{*}-c_{n n}^{(0)}\right)}=\frac{N_{n}^{n-1}\left(c_{n}^{n}-c_{n n}^{(0)}\right)}{\gamma\left(c^{*}-c_{n}{ }^{n}\right)\left(c^{*}-c_{n n}^{(0)}\right)} \leqslant 0
$$

Let us now assume that $\tau_{n} \in\left\{a_{3}, b_{s}\right\}$ and prove that $\tau_{n} \in\left\{a_{s+1}, b_{s+1}\right]$. Tn fact, if $\tau_{n} \geqslant\left(a_{s}+\right.$ $\left.b_{s}\right) / 2=\tau_{n}{ }^{\left(s^{v}\right.}$, then it follows from the above $A_{s} \geqslant \tau_{n} \geqslant \tau_{n}{ }^{(s)}$ and we select $a_{s+1}=\tau_{n}{ }^{(s)}, b_{s+1}=b_{s}$. Hence $\tau_{n} E\left[a_{s+1}, b_{s+1}\right]$. If $\tau_{n} \leqslant\left(a_{s}+b_{s}\right) / 2$ then $A_{s} \leqslant_{\pi_{n}} \varepsilon_{i} \tau_{n}^{(s)}$ and we select $a_{s+1}=a_{s}$ and $b_{s+1}=\tau_{n}{ }^{(s)}$. As previously, we have $\tau_{n} s\left\{a_{s+1}, b_{s+1}\right\rfloor$. Thns $\tau_{n}$ and $\tau_{n}{ }^{(s)} \in\left[a_{s}, b_{s}\right] s \geqslant 1$.

Since by definition $b_{s}-a_{s} \rightarrow 0$ as $s \rightarrow \infty$, hence $\boldsymbol{\tau}_{n}{ }^{(s)} \rightarrow \boldsymbol{\tau}_{n}$, as $s \rightarrow \infty$, and since $c_{i n}$ is continuously dependent on $\tau_{n}{ }^{(8)}$, then $c_{i n}{ }^{(8)} \rightarrow c_{i}{ }^{n}, i=0, \ldots, M$ as $s \rightarrow \infty$. The theorem is proved.

Theorem 3, If the conditions

$$
\begin{aligned}
& m_{1}>m_{2}>0, D>0, v^{*} \geqslant v^{i} \geqslant v_{0}>0,0 \leqslant\left(v^{i}-v^{i-1}\right) / \tau_{j} \leqslant P \\
& \gamma>v^{*} K_{0} /\left(c^{*}-c_{M^{0}}\right), c^{*}>c_{*}>0
\end{aligned}
$$

are satisfied, there exists a unique solution of the input problem (1.1).
Proof, Let us examine the sequence of grids $w_{p}, h_{p} \rightarrow 0$ with $p \rightarrow \infty$. For each grid we extend the definition of functions $c_{i}{ }^{i},\left(c_{i}{ }^{j}\right)_{x},\left(c_{i}\right)_{x x},\left(c_{i}\right)_{i}, N_{i}{ }^{i}$, and $\left(N_{i}{ }^{\prime}\right)_{t}$ linearly $/ 8 /$ over all $Q_{T}$, and denote them, respectively, by $c^{g}(x, t), y^{p}(x, t), r^{\prime \prime}(x, t), s^{\prime \prime}(x, t), N^{\prime}(x, t)$, and $R^{\prime \prime}$ $(x, t)$.

In addition we define the broken line

$$
l^{\prime \prime}(t)=j h+\left(t-t_{j}\right) h / \tau_{j}, t_{j} \leqslant t \leqslant t_{j+1}, j=1, \ldots, M
$$

Lemma 5 implies that $\left\{l^{p}\right\}$ is compact in $C[0, T]$, hence there exists a subsequence $l^{p_{k}}$ which uniformly converges to $l^{\circ}(t) \in C^{0}[0, T]$.

Using the Bernshtein estimates /8/ we find that $\left\{c^{p}\right\},\left\{y^{p}\right\},\left\{r^{p}\right\}$ and $\left\{s^{p}\right\}$, are compact in regions $G_{1 \delta}=\left\{(x, t): \delta \leqslant x \leqslant l^{\circ}(t)-\delta, \delta \leqslant t \leqslant T\right\}$ and $G_{2 \delta}=\left\{(x, t): l^{\circ}(t)+\delta \leqslant x \leqslant L-\delta, \delta \leqslant t \leqslant T\right\}$, while $\left\{N^{p}\right\},\left\{R^{p}\right\}$ is compact in $G_{20}$, where $\delta>0$ is any fairly small number. This implies the existence of subsequence of numbers which we also denote by $p_{k}$, such that $c^{p_{i}}, y^{p_{k}}, r^{p_{i k}}$, and $s^{p_{k}}$ converge, respectively, to some $c^{c}(x, t), y^{\prime}(x, t), r^{\circ}(x, t)$, and $s^{\prime \prime}(x, t)$ at any internal point $Q_{T}, x \neq l^{\circ}(t)$, and uniformly in $G_{1 \delta}$ and $G_{2 \delta}$ for any fairly small $\delta>0$. Similarly we have /8/ $\quad y(x, t)=c_{x}{ }^{2}(x, t), r^{*}(x, t)=c_{x x}^{c}(x, t), s^{3}(x, t)=c_{x}{ }^{\circ}(x, t)$

The proof of uniform convergence of $N^{p_{k}}$ and $R^{p_{i}}$ to $N^{0}(x, t)$, and $N_{t}^{0}(x, t), l(t) \leqslant x, L$ is similar. As in $/ 8 /$, we obtain that $c^{\circ}(x, t)$ and $V^{\circ}(x, t)$ satisfy the respective differential equations and boundary conditions in (1.1).

It follows from Lemmas 2, 3, 5, and 6 that $\left\{c ;\right.$ is compact in $Q_{i}$ and, consequently, $\left.c^{\prime \prime}\right\}$ uniformly converges in $Q_{T}$ to $c^{\prime}(x, t) G\left(Q_{T}\right)$, i.e. the first condition of junction on $l^{\circ}(t)$ is satisfied in the classical sense. From these lemmas we further have that $N^{p_{k}}$ and $R^{p_{k}}$ uniformly converge in $\left[l^{\nu}(t), L\right] \times[0, T]$ to $N^{\nu}, N_{t}{ }^{\circ} \in C$. The sequence $\left\{y^{p}\right\}$ is compact in $C[0, L]$ for any fixed $t \in[0, T]$, which follows from Lemmas 3 and 6 , and, consequently, $y^{p_{k}}\left(x, t_{0}\right)$ uniformly converges to $c_{x}\left(x, t_{0}\right)$ for any $t_{0} \in[0, T]$. This also implies the fulfilment of the conjunction condition for $c_{x}{ }^{\circ}$ on $l^{\circ}(t)$. Finally, taking into account the condition $N_{j}{ }^{j}=0$ and the convergence of $\left\{N^{p_{k}}\right\}$ and $\left\{l^{p}\right\}$, we obtain $N^{\circ}\left(l^{\circ}(t)+0, t\right)=0$.

Thus the set of three functions $c^{\circ}(x, t), N^{\circ}(x, t)$, and $l^{\circ}(t)$ is the solution of problem (1.1). It uniqueness is proved by the method of contractive mappings. The theorem is proved.

The authors thanks F. P. Vasil'ev for advice and interest in this work.

## REFERENCES

1. VERIGIN, N. N., On the kinetics of salt dissolution by water filtration in soils. Coll. Dissolution and Leaching of Salt in Rocks. Moscow, Gosstroiizdat, 1957.
2. SHUL'GIN, D. F. and MASHARIPOV, R., Computer forecasting the salt condition of salted soils under flushing. Uzbeksk. Geol., No.2, 1971.
3. VERIGIN, N. N., MASHARIPOV, R. and SHUL'GIN, D. F., Dissolution and flushing of salts in water-saturated soils. Vestn. S/X Nauki, No.l., 1977.
4. LADYZHENSKAIA, O. A., SOLONNIKOV, V. A., and URAT''TSFVA, N. N., Linear and Quasilinear Equations of the Parabolic Type. Moscow, "Nauka", 1967.
5. IL'IN, A. M., KALASHNIKOV, A. S., and OLEINIK, O. A., Second order linear equations of the parabolic type. Uspekhi Matem. Nauk, Vol. 17, No.3, 1962.
6. BUDAK, B. M., VASIL'EV, F. P., and USPENSKII, A. B., Different methods of solving certain boundary value problems of the Stefan type. Coll. Numerical Methods in Gasdynamics. Izd. MGU, No.4, 1965.
7. SAMARSKII, A. A., The Theory of Difference Schemes. Moscow, "Nauka", 1977.
8. PETROVSKII, I. G., Lectures on Equations with Partial Derivatives. Moscow, Fizmatgiz, 1961.
